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Summary	1	Direct tension	F F	Uniform	$\sigma = \frac{F}{A} \tag{9}$
	2	Bending	F <sub>1</sub> F <sub>2</sub> M A Bending moment diagram	-σ +σ	$\sigma = \pm \frac{M}{Z} = \pm \frac{My}{I}  (11)$
		Landrig	benang moment diagram	Neutral plane	For beams of rectangular
	3	Bending	$F_1$ $F_2$ $R_1$ $AR_2$ $R_1$ $F_1$ $R_2$ $R_1$ $R_2$ $R_1$ $R_2$ $R_1$ $R_2$ $R_1$ $R_2$ $R_1$ $R_2$ $R_2$ $R_1$ $R_2$ $R_2$ $R_2$ $R_3$ $R_2$ $R_2$ $R_3$ $R_2$ $R_2$ $R_3$ $R_2$ $R_2$ $R_3$ $R_2$ $R_3$ $R_2$ $R_3$ $R_2$ $R_3$ $R_2$ $R_3$ $R_2$ $R_3$ $R_3$ $R_2$ $R_3$ $R_$	+τ τ Neutral plane	cross-section: $\tau = \frac{3V}{2A} \qquad (12)$ For beams of solid circular cross-section: $\tau = \frac{4V}{3A} \qquad (13)$ For wide flange and I beams (approximately): $\tau = \frac{V}{a} \qquad (14)$
	4	Direct shear	F↓ t F	Uniform	$\tau = \frac{F}{A} \tag{15}$
	5	Torsion	<b>C</b>	τ	$\tau = \frac{T}{Zp} = \frac{Tc}{J}  (16)$
			•	•	·1











